

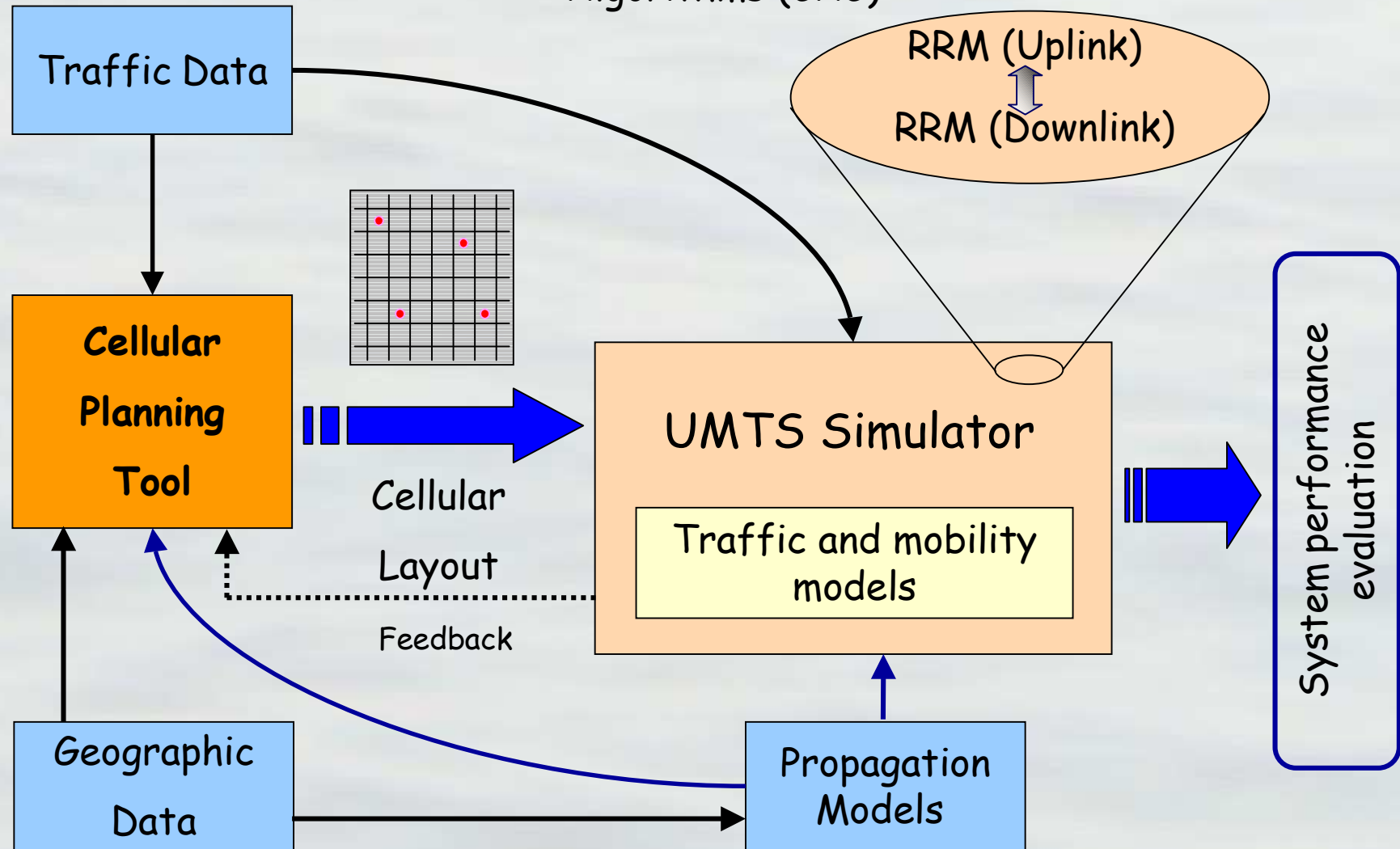


Presentation for:
**Radio Resource Management
Cellular Planning Tool**

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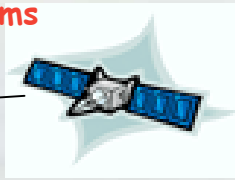
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Radio Resource Management Algorithms (CAC)



OBJECTIVE : Localize and configurate antennas in order to ensure required service level in the target area while minimizing deployment costs.

Candidate satellite beams

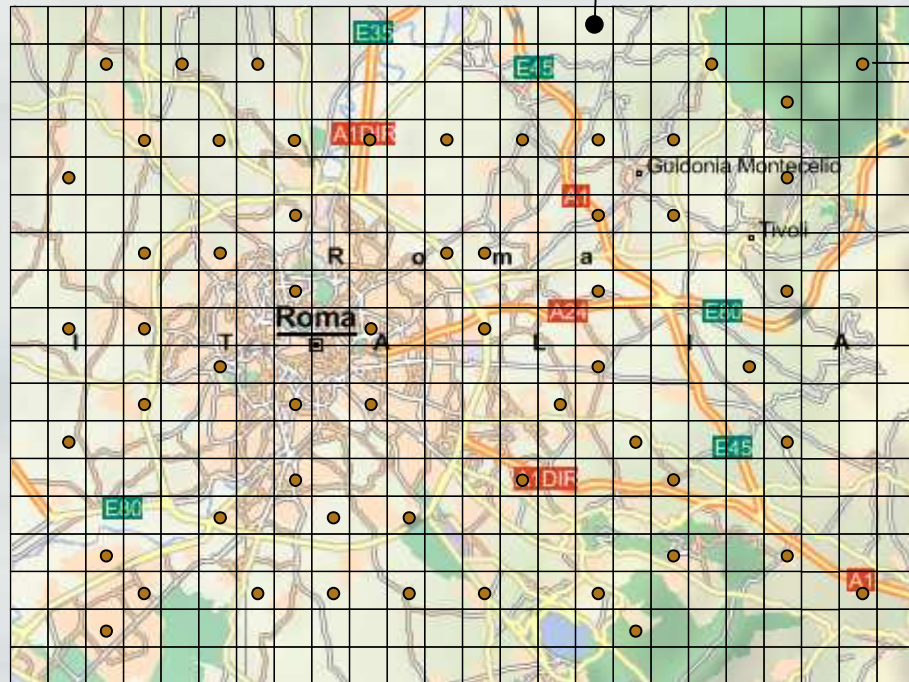


Test Point (TP)

Set of TP : \mathbf{R}

Location
Traffic demand for each service : T_r^s

Set of services : \mathbf{S}



Candidate t-location (special TP)

\mathbf{B} : set of candidate locations, both terrestrial and satellite

Activation variables:

$$y_b = \begin{cases} 1 & \text{if an antenna is activated in } b \\ 0 & \text{otherwise} \end{cases}$$

Assignment variables:

$$x_{rb} = \begin{cases} 1 & \text{if TP } r \text{ is assigned to } b \\ 0 & \text{otherwise} \end{cases}$$

Power variables:

$p_r^s \in [0, P_{MAX}]$: emitted power from mobiles located in TP r and requesting service s

continuous variables

target area

Problem formulation

Constranits

Standard facility location constraints

$$\rightarrow x_{rb} \leq y_b \quad \forall r \in R \quad \forall b \in B$$

$$\rightarrow \sum_{b \in B} x_{rb} = 1 \quad \forall r \in R$$

A TP can be assigned only to one active BS or satellite beam

Link-budget constraints

$$\rightarrow p_r^s / l_{rb} \geq \left(\sum_{k \in S} \sum_{i \in R} \nu^k T_i^k p_i^k / l_{ib} + N \right) \cdot SIR^s - M \cdot (1 - x_{rb})$$

Uplink

→ Downlink modeling is similar

Nearness constraints

$$\rightarrow x_{rb} + \sum_{k \in V(r,b)} x_{rk} \geq y_b$$

A TP is assigned to the nearest active BS or satellite beam

Set of candidate locations closer than b to TP r
(only for terrestrial sites)

Problem formulation

Objective function

B : set of candidate locations, both terrestrial and satellite

Minimization of total installation cost

$$\min \sum_{b \in B} f_b \cdot y_b + \sum_{b \in B} \sum_{r \in R} c_{rb} \cdot x_{rb} + \sum_{r \in R} c_{r(|B|+1)} x_{r(|B|+1)}$$

↓
↘
↗

Activation costs
Service cost
Non coverage costs

➔ "False station" To account for unassigned TPs

$$\left. \begin{matrix} y_{|B|+1} = 1 \\ f_{|B|+1} = 0 \end{matrix} \right\} \text{no activation cost}$$

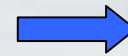
$$x_{r(|B|+1)} = \begin{cases} 1 & \text{if TP } r \text{ is not covered} \\ 0 & \text{otherwise} \end{cases}$$

- Problem: huge instances, difficult to solve exactly!

Solution algorithm

Problem analysis

If the vector of activated antenna is given

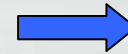


$$\bar{y}$$

$\bar{\mathbf{B}}$: set of activated antennas



Assignment vector is uniquely determined (thanks to nearness constraints)



$$\bar{x} = x(\bar{y})$$



Only power variable must be determined



$$\begin{cases} \tilde{A}p \geq N \cdot SIR \\ p_r \leq P_{MAX} \end{cases}$$



Interference system : system of linear inequalities in the power variables

Solution algorithm

Problem analysis

Interference system reduction

Received power variables : π_b is the power received at BS b , emitted by a TP assigned to it

$$\tilde{A}p \geq N \cdot SIR$$

$$\text{dim} : |R| \times |R|$$



$$\sum_{b \in \bar{B}} a_{rb} \cdot \pi_b = N \cdot SIR \quad \forall b \in \bar{B}$$

↑

$$\text{dim} : |\bar{B}| \times |\bar{B}|$$

Remark

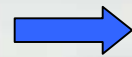
$$|\bar{B}| \ll |R|$$

The reduced system can be solved very efficiently

Solution algorithm

Solution algorithm

LOCAL SEARCH



To solve very efficiently large instances

- 1 Start with a current solution $(\bar{y}, \bar{x}, \bar{p})$
- 2 Select a proper neighborhood of the solution (exchange) $N(\bar{y}, \bar{x}, \bar{p})$
- 3 Find the best solution in the neighborhood (y^*, x^*, p^*)
- 4 Update current solution and go to 2